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April 25, 2007

AMENDMENTS TO THE CLAIMS:

The following listing of claims replaces all prior listings, and all prior versions, of claims in the application.

LISTING OF CLAIMS:

1. (Currently amended) A rotation system with three degrees of freedom comprising a rotor comprising a part or a whole of a sphere, an indication bar, at least one slider, at least one base, four shafts, six bearings, and three first to third guide rails,

wherein

said rotor includes said indication bar,

said first guide rail is installed on said base by using two said shafts and two said bearings,

said second guide rail and said third guide rail are installed on said base by using two remaining said shafts and four remaining said bearings, and

at least one said slider is installed on or concatenated with said indication bar, moreover wherein

said <u>second guide rail</u>rotor rotates centering around two said shafts supporting said <u>second</u>first guide rail, sliding said indication bar along said first guide rail,

said <u>first guide rail</u>rotor rotates centering around two said shafts supporting said first guide rail, sliding said indication bar along said second guide rail, and said rotor rotates centering around said indication bar, sliding at least one said

slider along said third guide rail.

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2. (Original) A rotation system with three degrees of freedom according to

claim 1, wherein said indication bar passes through slits, which are opened in at

least one of said first guide rail and a second guide rail.

3. (Previously presented) A rotation system with three degrees of freedom

according to claim 1, wherein

a fourth guide rail is installed on said indication bar, and

said slider slides along said fourth guide rail.

4. (Currently amended) A rotation system with three degrees of freedom

comprising a rotor comprising a part or a whole of a sphere, an indication bar, at

least two sliders, at least one base, four shafts, six bearings, and three first to third

guide rails,

wherein

said rotor comprises said indication bar,

said first guide rail is installed on said base by using two said shafts and two

said bearings,

said second guide rail and said third guide rail are installed on said base by

using two remaining said shafts and four remaining said bearings, and

at least two said sliders are installed on or concatenated with said indication

bar, moreover wherein

each of said second guide rail and said third guide railsaid rotor rotates

centering around two said shafts supporting said second first guide rail, sliding said

indication bar along said first guide rail,

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said <u>first guide rail</u>rotor rotates centering around two said shafts supporting

said firstsecond guide rail and said third guide rail, sliding at least two said sliders

along said second guide rail and said third guide railthese guide rails, and

__said rotor rotates centering around said indication bar, sliding at least two said

sliders along said second guide rail and said third guide rail.

5. (Original) A rotation system with three degrees of freedom according to

claim 4, wherein said indication bar passes through a slit, which is opened in said

first guide rail.

6. (Previously presented) A rotation system with three degrees of freedom

according to claim 4, wherein

a fourth guide rail and a fifth guide rail are installed on said indication bar, and

two said sliders slide along these said guide rails, respectively.

7. (Currently amended) A rotation system with three degrees of freedom

comprising a rotor comprising a part or a whole of a sphere, an indication bar, at

least two sliders, at least one base, four shafts, six bearings, and four first to third

and sixth guide rails,

wherein

said rotor comprises said indication bar,

said first guide rail and said sixth guide rail are installed on said base by using

two said shafts and two said bearings,

said second guide rail and said third guide rail are installed on said base by

using two remaining said shafts and four remaining said bearings, and

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at least two said sliders are installed on or concatenated with said indication

bar, moreover wherein

each of said second guide rail and said third guide railsaid rotor rotates

centering around two said shafts supporting said second first guide rail and said sixth

guide rail, sliding at least two said sliders along said first rail and said sixththese said

guide railrails,

each of said first guide rail and said sixth guide railsaid rotor rotates centering

around two said shafts supporting said first second guide rail and said third guide rail,

sliding at least two said sliders along said second guide rail and said thirdthese guide

railrails, and

said rotor rotates centering around said indication bar, sliding at least two said

sliders along said second guide rail and said third guide rail.

8. (Original) A rotation system with three degrees of freedom according to

claim 7, wherein at least two said sliders pass through slits, respectively, which are

opened in said first guide rail and said sixth guide rail.

9. (Previously presented) A rotation system with three degrees of freedom

according to claim 7, wherein

a fourth guide rail and a fifth guide rail are installed on said indication bar, and

two said sliders slide along these said guide rails, respectively.

10. (Previously presented) A rotation system with three degrees of freedom

according to claim 1,

wherein

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said indication bar is a pipe, and

at least one wire passes through said indication bar.

11. (Previously presented) A rotation system with three degrees of freedom

according to claim 1,

wherein all said shafts are installed on at least one said base so as to face

with each other every two shafts.

12. (Previously presented) A rotation system with three degrees of freedom

according to claim 1,

wherein

four said bearings are installed on at least one said base so as to face with

each other every two shafts,

two said shafts installed on a terminal of said second guide rail and said third

guide rail are installed on two said bearings installed on said base, respectively, and

two said bearings installed on another terminal of said second guide rail and

said third guide rail are installed on said shafts of said third guide rail and said

second guide rail, respectively.

13. (Previously presented) A rotation system with three degrees of freedom

according to claim 1,

wherein

four said bearings are installed on at least one said base so as to face with

each other every two shafts,

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two said shafts installed on both terminals of said second guide rail are

installed on two said bearings installed on said base, respectively, and

two said bearings installed on both terminal of said third guide rail are

installed on said shafts of said second guide rail, respectively.

14. (Previously presented) A rotation system with three degrees of freedom

according to claim 1,

wherein at least one encoder detects a direction of said rotor, by detecting at least

one rotation angle of said guide rails, said shafts and said bearings.

15. (Original) A rotation system with three degrees of freedom according to

claim 14, wherein at least one encoder detects said direction of said rotor, by

concatenating it to at least one of said guide rails, said shafts and said bearings via

plurality of gears.

16. (Previously presented) A rotation system with three degrees of freedom

according to claim 14, wherein each of at least one said encoder comprises an

actuator.

17. (Previously presented) A rotation system with three degrees of freedom

according to claim 1,

wherein at least one actuator rotates said rotor, by rotating at least one of said guide

rails, said shafts and said bearings.

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18. (Original) A rotation system with three degrees of freedom according to

claim 17, wherein at least one actuator rotates said rotor, by concatenating it to at

least one of said guide rails, said shafts and said bearings via plurality of gears.

19. (Previously presented) A rotation system with three degrees of freedom

according to claim 14, wherein a computer system calculates a rotation angle of said

rotor, by connecting at least one said encoder to said computer system.

20. (Previously presented) A rotation system with three degrees of freedom

according to claim 16, wherein a computer system rotates said rotor, by connecting

at least one said actuator to said computer system.

21. (Original) An artificial eye comprising a rotation system with three

degrees of freedom according to claim 20, wherein a camera taking a picture in a

direction opposite to said indication bar is embedded in said rotor.

22. (Original) An artificial eye according to claim 21, wherein an image

rotates by that said computer system memorizes said image taken by said camera,

and outputs each pixel of said image, exchanging an order of said pixels.